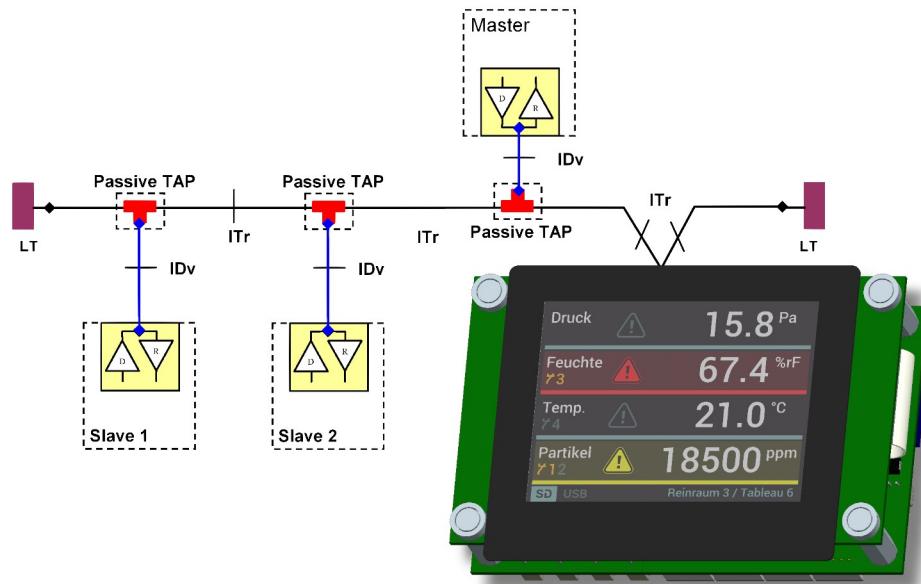




Modbus



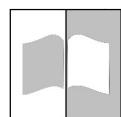
RoHS II  
COMPLIANT



## User Manual

### Modbus RTU

Protocol description  
for the TOUCH product line



## Masthead

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# 1 Introduction

The Modbus protocol is a communication protocol that is based on a Master/Slave architecture. All FISCHER products work in the operating mode Modbus RTU.

This manual is designed for readers with a basic understanding of the Modbus protocol. There are references to relevant specialist literature about this topic at the end of this manual.

## 1.1 Modbus infrastructure

Communication with the FISCHER units requires a serial two-wire bus (2W) in compliance with the EIA/TIA-485 standard. All connected units must be connected to a joint reference potential by means of a third (common) line. The bus is connected using a  $150\Omega$  0.5W resistor. The pull up/down resistors are usually set on the master. Usually, up to 32 slaves can be connected without a repeater.

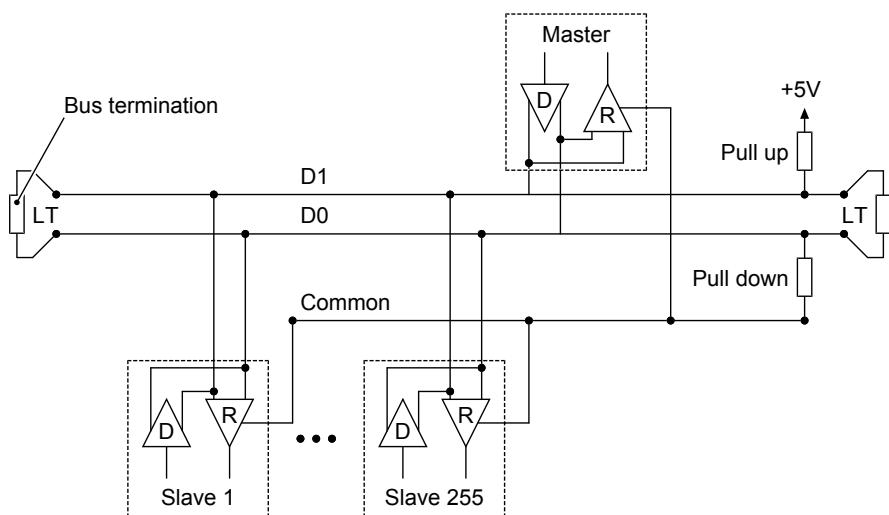


Fig. 1: Modbus infrastructure



### NOTICE

#### Passive TAP

If the units are connected via a Passive TAP (e.g. T-adapter connection), the units can be disconnected from the bus without interrupting the bus.

## 1.2 Modbus RTU Protocol

The Modbus RTU transfers data in a binary form. A single master and up to 255 slaves can be connected at the same time to the serial Modbus.

The following basic rules apply.

- A Modbus transaction is only initialised by the Master.
- At the same time, only one Modbus transaction takes place.
- The Slave never sends data without a request from the Master.
- Slaves cannot communicate with each other.

### 1.3 Modbus Transaction

A Modbus transaction comprises two parts. A request from the Master and a response from the Slave.

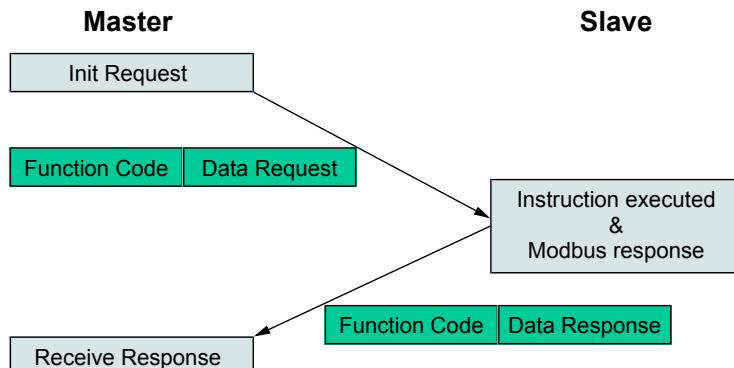


Fig. 2: Error-free request/response cycle

If an error occurs during a Modbus transaction, the Function Code is replaced with a special Function Code with an error indicator in the Modbus Response message and a more detailed description of the error in the data field is sent.

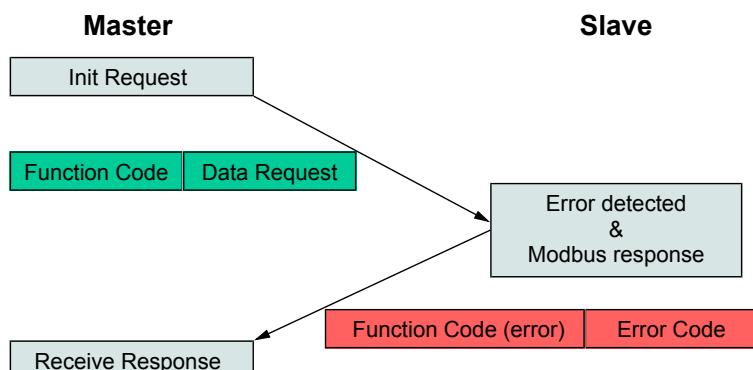


Fig. 3: Faulty request/response cycle

### 1.4 Modbus Frame

A Modbus data frame comprises two components.

- Protocol Data Unit (PDU )
- Application Data Unit (ADU )

The inner data structure is the PDU and additional data fields are added for the encapsulation of the frame in the respective protocol of the data transmission.

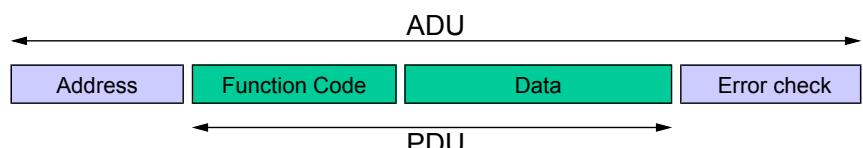


Fig. 4: MODBUS Frame

In the Modbus RTU protocol, the address field contains the Slave address. The address space comprises the addresses 1 to 255. If the Slave sends a Response, it positions its own address in the address field. This means that the Master 'knows' which Slave is sending. The Function Code states which action needs to be carried out. The following data field contains the Request and Response parameters. The error check field contains the result of a CRC review of the content of the transmission.

## 1.5 Modbus data transmission

In the RTU mode, each message is sent as a continuous binary flow of characters via the serial bus.

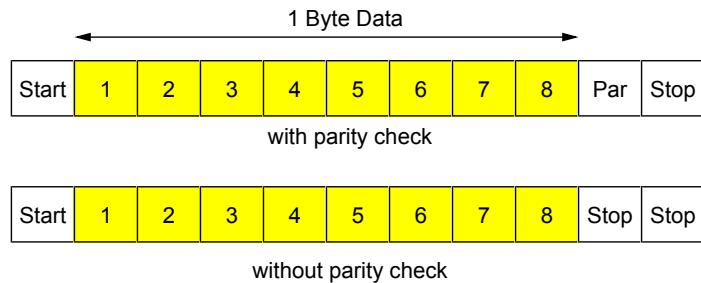


Fig. 5: Bit Sequence

The Even Parity is set as the default value for the parity bit. But an Odd Parity and No Parity can also be used. If No Parity is used, a further stop bit is added.

A Modbus message is set by the transferring unit in a so-called frame. The maximum size of a message is 256 byte. Start and end point of a frame are well defined. This allows the receiving unit to recognise the start and end of a message.

A transmission starts with a break of at least 3.5 characters (char.). Then the frames are sent. Each frame must be followed by a pause interval ( $t_{3.5}$ ) with a length of at least 3.5 characters before the next frame is sent. There must be a pause interval ( $t_{1.5}$ ) with a length of at least 1.5 characters between two characters. The entire transmission must be sent as a continuous flow of characters.

If the idle intervals are not satisfied, the character flow stops and the transmission is declared invalid.

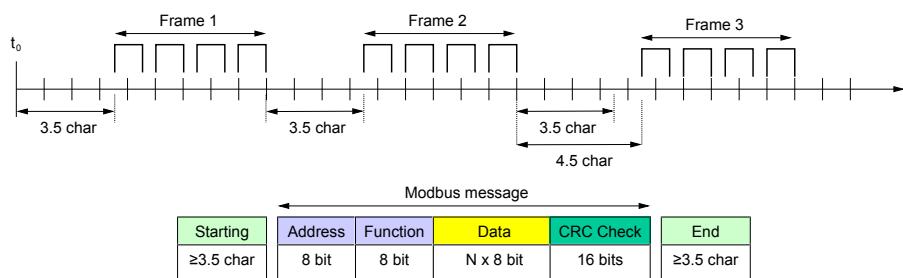


Fig. 6: Modbus Message Frame

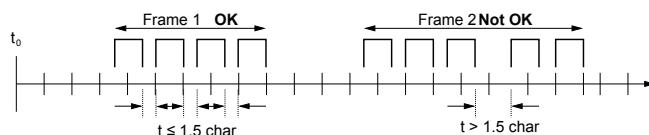


Fig. 7: Faulty transmission (example)

## 2 Functions

The Function Codes correspond to the [Modbus Application Protocol v1.1b3](#). The illustrations of messages only contain the PDU. Slave address and checksums are not shown. Messages that comprise several bits are transferred first with the byte with the highest value (MSB), followed by the byte with the lowest value (LSB).

In the case of transmission errors, messages with invalid checksums or if a broadcast address is used, no response is sent by the Slave.

### 2.1 General

The Modbus protocol has a series of options for access to the data:

Type	Access	Name	Code	Sub Code
Data	Bit	Read Coils	01	
		Read Discrete Inputs	02	
	16 Bit	Read Holding Register	03	
		Read Input Register	04	
		Write Single Register	06	
		Write Multiple Register	16	
		Mask Write Register	22	
		Read/Write Multiple Registers	23	
Diagnosis		Diagnosis	08	00; 10-15
		Report Server ID	17	
Other		Encapsulated Interface Transport:	43	14
		Read Device Identification		

#### Note!

The FISCHER units only have one block for the four functions Read Coils, Read Input Register, Read Holding Register and Read Input Register in their application memory.

- 'Coils' and 'Discrete Inputs' can be read with both the Function Code 01 and also with the Function Code 02.
- 'Input Register' and 'Holding Register' can be read with both the Function Code 03 and also with the Function Code 04.

### 2.2 Bit access

#### 2.2.1 Function Code [01] "Read Coils"

This Function Code is used to read the digital outputs.

##### Request

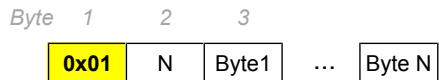


Byte	Field name	Size	Value range
1	Function Code	1 byte	0x01
2.3	Start Address	2 bytes	0x0000 to 0xFFFF
4.5	Number of outputs (coils)	2 bytes	1 to 2000 (0x7D0)

## Response

The states of the digital outputs are summarised as bytes in the response. The number of bytes (N) is the result of the number of outputs divided by 8. If there is a rest, the number of bytes increases ( $N=N+1$ ).

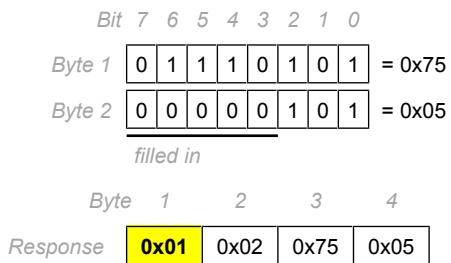
The states of the digital outputs from the bit with the lowest value are saved within a byte. A bit value of 0 corresponds to the status OFF; a bit value of 1 corresponds to the status ON.



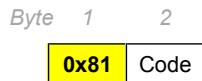
Byte	Field name	Size	Value range
1	Function Code	1 byte	0x01
2	Number of bytes	1 byte	N
3...	State of the outputs	N Bytes	8 Bit value

### Example:

- Number of outputs: 11
- Number of bytes: 2



## Error



Byte	Field name	Size	Value range
1	Function Code (error)	1 byte	0x81
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format; the number of requested outputs is greater than 2000

## 2.2.2 Function Code [02] "Read Discrete Inputs"

This Function Code is used to read the digital inputs.

### Request

The request contains the address of the first bit that is to be read and the number of bits that need to be read.



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x02
2..3	Start Address	2 bytes	0x0000 to 0xFFFF
4..5	Number of inputs	2 bytes	1 to 2000 (0x7D0)

### Response

The states of the digital inputs are summarised as bytes in the response. The number of bytes (N) is the result of the number of inputs divided by 8. If there is a rest, the number of bytes increases ( $N=N+1$ ).

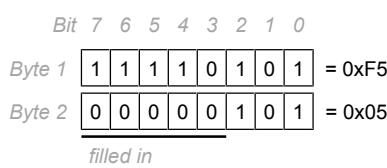
The states of the digital inputs from the bit with the lowest value are saved within a byte. A bit value of 0 corresponds to the status OFF; a bit value of 1 corresponds to the status ON.



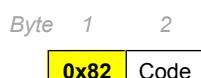
Byte	Field name	Size	Value range
1	Function Code	1 byte	0x02
2	Number of bytes	1 byte	N
3...	Number of inputs	N Bytes	8 Bit value

#### Example:

- Number of inputs: 11
- Number of bytes: 2



### Error



Byte	Field name	Size	Value range
1	Function Code (error)	1 byte	0x82
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format; the number of requested inputs is greater than 2000

## 2.3 16 Bit Register Access

### 2.3.1 Function Code [03] "Read Holding Register"

- Request**
- This Function Code is used to read the Holding Register. The maximum possible number of registers that can be addressed in one message is 125.
- The request contains the address of the first register that is to be read and the number of registers that need to be read. The addressing of the register starts with 0; the numbering of the registers starts with 1.

Byte	1	2	3	4	5
	<b>0x03</b>	MSB	LSB	MSB	LSB

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x03
2.3	Start Address	2 bytes	0x0000 to 0xFFFF
4.5	Number of registers	2 bytes	0x0001 to 0x007D (1...125)

- Response**
- The response contains two bytes for each read register; therefore the number of bytes is twice the number of registers (N).

Byte	1	2	3	4	...		
	<b>0x03</b>	2N	MSB	LSB	...	MSB	LSB

Register 1    Register N

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x03
2	Number of bytes	2 bytes	2N
3.4	Holding Register	N x 2 Byte	16 Bit value

### Error

Byte	1	2
	<b>0x83</b>	Code

Byte	Field name	Size	Value range
1	Function Code (error)	1 byte	0x83
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format; the number of requested registers is greater than 125

### Example:

- Export Holding Register 108 to 110
- Content Register 108= 0x000A
- Content Register 109= 0x000B
- Content Register 110= 0x000C

Byte	1	2	3	4	5	6	7	8
Request	<b>0x03</b>	0x00	0x6B	0x00	0x03			
Response	<b>0x03</b>	0x06	0x00	0x0A	0x00	0x0B	0x00	0x0C

Request		Response	
Field name	Value	Field name	Value
Function Code	0x03	Function Code	0x03
Start Address MSB	0x00	Number of bytes	0x06
Start Address LSB	0x6B	Holding Register 108 MSB	0x00
Number of Registers MSB	0x00	Holding Register 108 LSB	0x0A
Number of Registers LSB	0x03	Holding Register 109 MSB	0x00
		Holding Register 109 LSB	0x0B
		Holding Register 110 MSB	0x00
		Holding Register 110 LSB	0x0C

### 2.3.2 Function Code [04] "Read Input Register"

This Function Code is used to read the input register. The maximum possible number of registers that can be addressed in one message is 125.

#### Request

The request contains the address of the first register that is to be read and the number of registers that need to be read. The addressing of the register starts with 0; the numbering of the registers starts with 1.



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x04
2.3	Start Address	2 bytes	0x0000 to 0xFFFF
4.5	Number of registers	2 bytes	0x0001 to 0x007D (1...125)

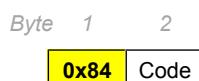
#### Response

The response contains two bytes for each read register; therefore the number of bytes is twice the number of registers.



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x04
2	Number of bytes	2 bytes	2N
3.4	Content Register	N x 2 Byte	16 Bit value

#### Error



Byte	Size	Value range
1	Function Code (error)	1 byte
2	Error code	1 byte

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format; the number of requested registers is greater than 125

**Example:**

- Export Content Register 9
- Content Register 9= 0x000A

	Byte	1	2	3	4	5
Request		0x04	0x00	0x08	0x00	0x01
Response		0x04	0x02	0x00	0x0A	

Request		Response	
Field name	Value	Field name	Value
Function Code	0x04	Function Code	0x04
Start Address MSB	0x00	Number of bytes	0x02
Start Address LSB	0x08	Input Register 9 MSB	0x00
Number of Registers MSB	0x00	Input Register 9 LSB	0x0A
Number of Registers LSB	0x01		

**2.3.3 Function Code [06] "Write Single Register"**

This Function Code is used to write a single Holding register.

**Request**

The request contains the address of the register that is to be written and value that is to be written.

Byte	1	2	3	4	5
	0x06	MSB	LSB	MSB	LSB

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x06
2.3	Register Address	2 bytes	0x0000 to 0xFFFF
4.5	Register Value	2 bytes	0x0000 to 0xFFFF

**Response**

The response contains the address register and the written value.

Byte	1	2	3	4	5
	0x06	MSB	LSB	MSB	LSB

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x06
2	Register Address	2 bytes	0x0000 to 0xFFFF
3.4	Register Value	2 bytes	0x0000 to 0xFFFF

**Error**

Byte	1	2
	0x86	Code

Byte	Size	Value range
1	Function Code (error)	1 byte
2	Error code	1 byte Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format

### Example:

- Write register 2
- Value that needs to be written = 0x0003

Byte	1	2	3	4	5
Request	0x06	0x00	0x01	0x00	0x03
Response	0x06	0x00	0x01	0x00	0x03

Request		Response	
Field name	Value	Field name	Value
Function Code	0x06	Function Code	0x06
Register Address MSB	0x00	Register Address MSB	0x00
Register Address LSB	0x01	Register Address LSB	0x01
Register Value MSB	0x00	Register Value MSB	0x00
Register Value LSB	0x03	Register Value LSB	0x03

### 2.3.4 Function Code [16] "Write Multiple Registers"

This Function Code is used to write a block of sequential registers. The maximum possible number of registers that can be addressed in one message is 123.

#### Request

The request contains the address of the first register that is to be written and the number of registers that need to be written. The addressing of the register starts with 0; the numbering of the registers starts with 1.

Byte	1	2	3	4	5	6	7	8	...	MSB	LSB
	0x10	MSB	LSB	MSB	LSB	2N	MSB	LSB		MSB	LSB

\_\_\_\_\_  
Register 1    Register N

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x10
2..3	Start Address	2 bytes	0x0000 to 0xFFFF
4..5	Number of registers	2 bytes	0x0001 to 0x007B (1...123)
6	Number of bytes	1 byte	2 x N
7..8	Register Value	N x 2 Byte	Value

#### Response

The response contains the start address and the number of written registers.

Byte	1	2	3	4	5
	0x10	MSB	LSB	MSB	LSB

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x10
2..3	Start Address	2 bytes	0x0000 to 0xFFFF
4..5	Number of Registers	2 bytes	0x0001 to 0x007B (1...123)

## Error



Byte		Size	Value range
1	Function Code (error)	1 byte	0x90
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format; the number of requested registers is greater than 123; the number of data bytes does not match the number of registers

### Example:

- Write 2 registers
- Start Address = 0x0001
- Content Register 2= 0x000A
- Content Register 3= 0x0102

Byte	1	2	3	4	5	6	7	8	9	10
Request	0x10	0x00	0x01	0x00	0x02	0x04	0x00	0xA0	0x01	0x02
Response	0x10	0x00	0x01	0x00	0x02					

Request		Response	
Field name	Value	Field name	Value
Function Code	0x10	Function Code	0x10
Start Address MSB	0x00	Start Address MSB	0x00
Start Address LSB	0x01	Start Address LSB	0x01
Number of Registers MSB	0x00	Number of Registers MSB	0x00
Number of Registers LSB	0x02	Number of Registers LSB	0x02
Number of bytes	0x04		
Register Value MSB	0x00		
Register Value LSB	0xA0		
Register Value MSB	0x01		
Register Value LSB	0x02		

### 2.3.5 Function Code [22] "Mask Write Register"

This Function Code is used to write individual bits into a Holding Register. Two masks are used for this:

- And\_Mask and
- Or\_Mask

The function algorithm is as follows:

Result = (Register value AND And\_Mask) OR (Or\_Mask AND (NOT And\_Mask))

**Example:**

		Hex	Binary
Register Value		12	0001 0010
And_Mask	AND F2	1111 0010	→ 0001 0010
Or_Mask		25	0010 0101
NOT And_Mask	AND 0D	0000 1101	OR
Result		17	0001 0111 ←

- If the OR\_Mask has the value zero, the result is the logical AND from the value register and the AND\_Mask.
- If, in contrast, the And\_Mask has the value zero, the result is identical to the content of the OR\_mask.

**Request**

The request contains the address of the register that is to be written and the masks.



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x16
2..3	Register Address	2 bytes	0x0000 to 0xFFFF
4..5	And_Mask	2 bytes	0x0000 to 0xFFFF
6..7	Or_Mask	2 bytes	0x0000 to 0xFFFF

**Response**

The response is an echo of the request.



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x16
2..3	Register Address	2 bytes	0x0000 to 0xFFFF
4..5	And_Mask	2 bytes	0x0000 to 0xFFFF
6..7	Or_Mask	2 bytes	0x0000 to 0xFFFF

**Error**

Byte		Size	Value range
1	Function Code (error)	1 byte	0x90
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format;

**Example:**

- Write register 5
- And\_Mask = 0x00F2
- Or\_Mask = 0x0025

Byte	1	2	3	4	5	6	7
Request	0x16	0x00	0x04	0x00	0xF2	0x00	0x25
Response	0x16	0x00	0x04	0x00	0xF2	0x00	0x25

Request	Response		
Field name	Value	Field name	Value
Function Code	0x16	Function Code	0x16
Register Address MSB	0x00	Register Address MSB	0x00
Register Address LSB	0x04	Register Address LSB	0x04
And_Mask MSB	0x00	And_Mask MSB	0x00
And_Mask LSB	0xF2	And_Mask LSB	0xF2
Or_Mask MSB	0x00	Or_Mask MSB	0x00
Or_Mask LSB	0x25	Or_Mask LSB	0x25

**2.3.6 Function Code [23] "Read/Write Register"**

This Function Code is used to write new values in the Holding register and then export them. The maximum possible number of registers that can be written and/or read in one message is:

- Write: 121 registers
- Read: 125 registers

**Request**

The request contains the address of the first register that is to be read, the number of the register that is to be read, the address of the first written registers, the number of registers that need to be written, the number of transferred bytes and the new values. Each new register value comprises two bytes. N corresponds to the number of the register that is to be written.

Byte	1	2	3	4	5	6	7	8	9	10	11	12	...	MSB	LSB
0x17	MSB		LSB		MSB		LSB		MSB		LSB		MSB		

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x17
2..3	READ Start Address	2 bytes	0x0000 to 0xFFFF
4..5	READ Number of Registers	2 bytes	0x0000 to 0x007D (1...125)
6..7	WRITE Start Address	2 bytes	0x0000 to 0xFFFF
8..9	WRITE Number of Registers	2 bytes	0x0000 to 0x0079 (1...121)
10	WRITE Number of bytes	1 byte	2 x N
11..12	WRITE Register Value	N x 2 Byte	Value

**Response**

The response contains the number N of the read registers and their values.

Byte	1	2	3	4	...	MSB	LSB	
0x17	2N'		MSB		LSB		MSB	

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x17
2	Number of bytes	1 byte	2 x N'
3..4	READ Register Value	N' x 2 Byte	Value

**Error**

Byte	1	2
	<b>0x97</b>	Code

Byte	Size	Value range
1	Function Code (error)	1 byte
2	Error code	1 byte

The following error codes are possible:

0x01	The function is not supported
0x02	An invalid address is referenced
0x03	The request does not correspond to the expected format; the number of requested registers is greater than 121 and/or 125; the number of data bytes does not match the number of registers

**Example:**

READ:

- 6 Registers
- Start Address Register 4 = 0x0003
- Values: 0x00FE, 0x0ACD, 0x0001, 0x0003, 0x000D, 0x00FF

WRITE:

- 3 Registers
- Start Address Register 15 = 0x000E
- All values: 0x00FF

Byte	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Request	<b>0x17</b>	0x00	0x03	0x00	0x06	0x00	0x0E	0x00	0x03	0x06	0x00	0xFF	0x00	0xFF	0x00	0xFF
Response	<b>0x17</b>	0x0C	0x00	0xFE	0x0A	0xCD	0x00	0x01	0x00	0x03	0x00	0x0D	0x00	0x00	0xFF	

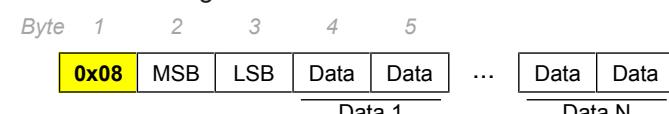
Request		Response	
Field name	Value	Field name	Value
Function Code	0x17	Function Code	0x17
READ Start Address MSB	0x00	Number of registers	0x0C
READ Start Address LSB	0x03	READ Register Value MSB	0x00
READ Number of Registers MSB	0x00	READ Register Value LSB	0xFE
READ Number of Registers LSB	0x06	READ Register Value MSB	0x0A
WRITE Start Address MSB	0x00	READ Register Value LSB	0xCD
WRITE Start Address LSB	0x0E	READ Register Value MSB	0x00
WRITE Number of Registers MSB	0x00	READ Register Value LSB	0x01
WRITE Number of Registers LSB	0x03	READ Register Value MSB	0x00
WRITE Number of bytes	0x06	READ Register Value LSB	0x03

Request		Response	
Field name	Value	Field name	Value
WRITE Register Value MSB	0x00	READ Register Value MSB	0x00
WRITE Register Value LSB	0xFF	READ Register Value LSB	0x0D
WRITE Register Value MSB	0x00	READ Register Value MSB	0x00
WRITE Register Value LSB	0xFF	READ Register Value LSB	0xFF
WRITE Register Value MSB	0x00		
WRITE Register Value LSB	0xFF		

## 2.4 Diagnosis

### 2.4.1 Function Code [08] "Diagnostic"

#### Request



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x08
2.3	Sub-function	2 bytes	Code see table
4.5	Data	N x 2 Byte	

#### Sub-function

00	0x0000	"Read Query Data"
10	0x000A	"Clear Counters and Diagnostic Registers"
11	0x000B	"Return Bus Message Count"
12	0x000C	"Return Bus Communication Error Count"
13	0x000D	"Return Bus Exception Error Count"
14	0x000E	"Return Server Message Count"
15	0x000F	"Return Server No Response Count"

#### Sub-function [00] "Read Query Data"

The data bytes from the request are returned in the response.

Sub-function	Data (Request)	Data (Response)
00 00	User-defined	Echo Data (Request)

#### Sub-function [10] "Clear Counters and Diagnostic Registers"

All counters are reset to 0. The response contains the data bytes from the request.<sup>(1)</sup>

Sub-function	Data (Request)	Data (Response)
00 0A	00 00	Echo Data (Request)

#### Sub-function [11] "Return Bus Message Count"

The number of recognised messages on the bus that are returned since the last start of the unit.

Sub-function	Data (Request)	Data (Response)
00 0B	00 00	Number of messages

<sup>(1)</sup> Comm.: The counters are also reset when the supply is switched on.

**Sub-function [12] "Return Bus Communication Error Count"**

The number of recipient errors and messages with invalid checksum (CRC) is sent back.

Sub-function	Data (Request)	Data (Response)
00 0C	00 00	Number of errors

**Sub-function [13] "Return Bus Exception Error Count"**

The number of error responses generated by this unit since it was started last.

Sub-function	Data (Request)	Data (Response)
00 0D	00 00	Number of error responses

**Sub-function [14] "Return Server Message Count"**

The number of messages addressed to the unit is returned.

Sub-function	Data (Request)	Data (Response)
00 0E	00 00	Number of messages

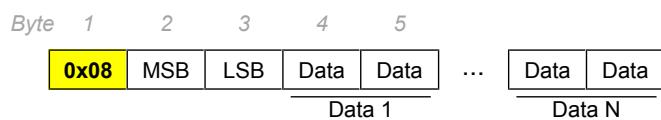
**Sub-function [15] "Return Server No Response Count"**

The number of requests to which no response was sent is returned.

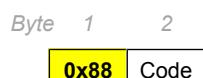
Sub-function	Data (Request)	Data (Response)
00 0F	00 00	Number of requests without a response

**Response**

The response corresponds to the request, however the content and number of data bytes depends on the executed diagnosis function (see above).



Byte	Field name	Size	Value range
1	Function Code	1 byte	0x08
2.3	Sub-function	2 bytes	
4.5	Data	N x 2 Byte	

**Error**

Byte	Size	Value range
1	1 byte	0x88
2	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x03	The request does not correspond to the expected format;

### 2.4.2 Function Code [17] "Report Server ID"

#### Request

Byte 1

**0x11**

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x11

#### Response

The response comprises one byte (number of bytes) and five data bytes. The first four data bytes contains the unit code, the last data byte is always 0xFF.

Byte 1 2 3 4 5 6 7

<b>0x11</b>	0x05	Byte1	Byte2	Byte3	Byte4	0xFF
-------------	------	-------	-------	-------	-------	------

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x11
2	Number of bytes	1 byte	0x05
3-6	Byte 1 ... Byte 4	4 byte	Code see table
7	Close	1 byte	0xFF

Appliance,	Byte 1	Byte 2	Byte 3	Byte 4
EA15	0xEA	0x15	0xEA	0x15
EA16	0xEA	0x16	0xEA	0x16

#### Error

Byte 1 2

<b>0x91</b>	Code
-------------	------

Byte	Field name	Size	Value range
1	Function Code (error)	1 byte	0x91
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x03	The request does not correspond to the expected format

## 2.5 Other functions

### 2.5.1 Function Code [43/14] "Read Device Identification"

This Function Code is used to read certain information about identification of the unit. The following object types are used in the FISCHER units:

Object ID	Object Name	Type	Category
0x00	VendorName	ASCII String	Basic
0x01	ProductCode	ASCII String	Basic
0x02	MajorMinorRevision	ASCII String	Basic
0x03	VendorUrl	ASCII String	Regular
0x04	ProductName	ASCII String	Regular
0x05	ModelName	ASCII String	Regular
0x06	UserApplicationName	ASCII String	Regular

**NOTICE! There are no objects of the Extended category.**

## Request

Byte	1	2	3	4
	<b>0x2B</b>	<b>0x0E</b>	DevID	ObjID

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x2B
2	MEI Typ <sup>+</sup>	1 byte	0x0E
3	Read Device ID Code	1 byte	01 / 02 / 04
4	Object ID	1 byte	0x00 to 0xFF

<sup>+</sup>) MEI = Modbus Encapsulated Interface

### Read Device ID

The Read Device ID Code (DevID) serves to specify the access. If the code is not correct, an error message with the code 0x03 is sent.

01	Access to objects of the Basic category	stream access
02	Access to objects of the Regular category	stream access
04	Access to a single object	individual access

If the length of the requested information exceeds the maximum possible length of the PDU, several transactions (Request/Response) must be carried out.

### Object ID

The Object ID Code states on which object of the 'stream access' should start. If the Object ID does not match the existing objects, the 'stream access' starts with the first object of the category. In the event of an 'individual access', an error message is generated with the error code 0x02.

## Response

The response comprises several bytes with status information followed by a list with the requested object information.

Byte	1	2	3	4	5	6	7	1	...	$k_0$	1	...	$k_N$					
	<b>0x2B</b>	<b>0x0E</b>	DevID	Conf	Follow	Next	Num	ObjID	Len	Val	...	Val	...	ObjID	Len	Val	...	Val

Byte	Field name	Size	Value range
1	Function Code	1 byte	0x2B
2	MEI Type	1 byte	0x0E
3	Read Device ID Code	1 byte	01 / 02 / 03 / 04
4	Conformity Level	1 byte	0x83
5	More Follows	1 byte	0x00 / 0xFF
6	Next Object ID	1 byte	Object ID Number
7	Number of Objects	1 byte	

*List of object data*

Object(N).ID	1 byte
Object(N).Length	1 byte
Object(N).Value	k Byte

### Conformity Level

The Conformity Level specifies the information category and the access type that is supported.

0x83	Extended Identification	stream and individual access
------	-------------------------	------------------------------

## More Follows

If the length of the requested information exceeds the maximum possible length of the PDU, several transactions (Request/Response) must be carried out. The 'More Follows' byte signalises whether or not further requests are required to transfer all information.

0x00	no further objects	
0xFF	other objects available	other transaction necessary

## Next Object ID

If a further transaction is required (More Follows = FF), the Object ID for the following Request is stated at this point.

Otherwise (More Follows = 00) this value is useless and is set to 00.

## Number of Objects

This byte states the number N of the objects that are transferred in the response. In the case of 'individual access' the number of objects is = 01.

## List of object data

Object(0).ID	Object ID of the first object in the response
Object(0).Length	Length of the object
Object(0).Value	Value of the object
...	
Object(N).ID	Object ID of the last object in the response
Object(N).Length	Length of the object
Object(N).Value	Value of the object

## Error

Byte	1	2
	0xAB	Code

Byte	Field name	Size	Value range
1	Function Code (error)	1 byte	0xAB (0x2B + 0x80)
2	Error code	1 byte	Code see table

The following error codes are possible:

0x01	The function is not supported
0x02	Invalid address (Object ID)
0x03	Invalid value (Read Device ID)

## An Example

Request		Response	
Field name	Value	Field name	Value
Function Code	0x2B	Function Code	0x17
MEI Type	0x0E	MEI Type	0x0E
Read Device ID Code	0x01	Read Device ID Code	0x01
Object ID	0x00	Conformity Level	0x83
		More Follows	0x00
		Next Object ID	0x00
		Number of Objects	0x03
		Object(0).ID	0x00
		Object(0).Length	0x0C
		Object(0).Value	FISCHER GmbH
		Object(1).ID	0x01

Request		Response	
Field name	Value	Field name	Value
	Object(1).Length		0x04
	Object(1).Value		<b>EA15</b>
	Object(2).ID		0x02
	Object(2).Length		0x04
	Object(2).Value		<b>V1.0</b>

## 3 Data types

### 3.1 Integer (16 Bit)

- Standard format for register
- Comprises two bytes in a Modbus message
- The higher-valued byte (Bits 8 to 15) is always sent first
- The two-complement format is used for integers with a preceding sign.

	Value range
unsigned Integer	0 ... 65535
signed Integer	-32768 ... +32767

### 3.2 Integer (32 Bit)

- Corresponds to the standard register format with an extended value range.
- A 32 Bit large number comprises two registers (four bytes).
- The byte sequence can be changed between the Big Endian- (the value with the highest value first) and the Little Endian format (the value with the lowest value first). (see Register 10207 [▶ 36])

**Example:**

$$284454020_{10} = 11223344_{16}$$

Format	Reg. 1	Reg. 1	Reg. 2	Reg. 2
	MSB	LSB	MSB	LSB
Big Endian	0x11	0x22	0x33	0x44
Little Endian	0x44	0x33	0x22	0x11

### 3.3 Float

- Floating comma figures are transferred in the IEEE-475 Single Precision format.
- It comprises two registers (four bytes).
- The byte sequence can be changed between the Big Endian- (the value with the highest value first) and the Little Endian format (the value with the lowest value first). (see Register 10207 [▶ 36])

**Example:**

$$1234.56_{10} = 449A51EC_{16}$$

Format	Reg. 1	Reg. 1	Reg. 2	Reg. 2
	MSB	LSB	MSB	LSB
Big Endian	0x44	0x9A	0x51	0xEC
Little Endian	0xEC	0x51	0x9A	0x44

### 3.4 Character

- Character chains are transferred with two characters per register each
- The preceding sign is saved in the higher value byte (MSB) and the following characters in the lower value byte (LSB) of the register.
- The last character of character chain with an uneven length is always a zero (0x00).

**Example:**

Character string = "FISCHER"

Reg. 1	Reg. 1	Reg. 2	Reg. 2	Reg. 3	Reg. 3	Reg. 4	Reg. 4
MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB
'F'	'I'	'S'	'C'	'H'	'E'	'R'	'0'
0x46	0x49	0x53	0x43	0x48	0x45	0x52	0x00

## 4 Addresses

### 4.1 Bit values



#### NOTICE

No differentiation is made between "Coils" and "Discrete inputs". All bit values can be read equally with the Function Codes 01 "Read Coils" and 02 "Read Discrete Inputs". Bit values cannot be written.

#### 4.1.1 Switching outputs

Bit No.	Adr.	Description	Status	
			ON	OFF
1	0	Switching output 1	1	0
2	1	Switching output 2		
3	2	Switching output 3		
4	3	Switching output 4		

#### 4.1.2 Alarm messages

##### Channel1

Bit No.	Adr.	Description	Status	
			ON	OFF
5	4	Message/colour change: low/red	1	0
6	5	Message/colour change: low/yellow		
7	6	Message/colour change: ok/green		
8	7	Message/colour change: high/yellow		
9	8	Message/colour change: high/red		
10	9	Acoustic alarm: low		
11	10	Acoustic alarm: high		
12	11	Acknowledge acoustic alarm		
13	12	not used		0
		...		
20	19	not used		0

##### Channel2

Bit No.	Adr.	Description	Status	
			ON	OFF
21	20	Message/colour change: low/red	1	0
22	21	Message/colour change: low/yellow		
23	22	Message/colour change: ok/green		
24	23	Message/colour change: high/yellow		
25	24	Message/colour change: high/red		
26	25	Acoustic alarm: low		
27	26	Acoustic alarm: high		
28	27	Acknowledge acoustic alarm		
29	28	not used		0
		...		
36	35	not used		0

**Channel3**

Bit No.	Adr.	Description	Status	
			ON	OFF
37	36	Message/colour change: low/red	1	0
38	37	Message/colour change: low/yellow		
39	38	Message/colour change: ok/green		
40	39	Message/colour change: high/yellow		
41	40	Message/colour change: high/red		
42	41	Acoustic alarm: low		
43	42	Acoustic alarm: high		
44	43	Acknowledge acoustic alarm		
45	44	not used		0
		...		
52	51	not used		0

**Channel4**

Bit No.	Adr.	Description	Status	
			ON	OFF
53	52	Message/colour change: low/red	1	0
54	53	Message/colour change: low/yellow		
55	54	Message/colour change: ok/green		
56	55	Message/colour change: high/yellow		
57	56	Message/colour change: high/red		
58	57	Acoustic alarm: low		
59	58	Acoustic alarm: high		
60	59	Acknowledge acoustic alarm		
61	60	not used		0
		...		
68	67	not used		0

## 4.2 16 Bit Register



### NOTICE

No differentiation is made between "Input Registers" and "Holding Registers". All values can be read equally with the Function Codes 04 "Read Input Registers" and 03 "Read Holding Registers".

The register 1 to 9999 can only be read. The remaining registers ( $\geq 10000$ ) allow write/read access.

If an invalid value is written in a register, its original value is retained. The number of the first invalid parameter can be called up via the Register 1015. If a zero (0) is saved here, the last written configuration is valid.

#### Data type abbreviations

Type	Abb.	Description
Float	Float	Floating point number
unsigned Integer	uINT	Integer without sign
signed Integer	INT	Integer with sign
Character	char	Character string

### 4.2.1 Measured values

#### NOTICE! Read-only access

Reg. No.	Adr.	No. of Format Reg.	Description
1	0	2	Float
3	2	2	Float
5	4	2	Float
7	6	2	Float

### 4.2.2 Input signals

#### NOTICE! Read-only access

Reg. No.	Adr.	No. of Format Reg.	Description
9	8	2	Float
11	10	2	Float
13	12	2	Float
15	14	2	Float

### 4.2.3 Output signals

#### NOTICE! Read-only access

Reg. No.	Adr.	No. of Format Reg.	Description
17	16	2	Float
19	18	2	Float
21	20	2	Float
23	22	2	Float

#### 4.2.4 Switching outputs

**NOTICE!** Read-only access

Reg. No.	Adr.	No. of Format Reg.	Description	Value ON	Value OFF
25	24	1	uINT	Status switch output 1	1 0
26	25	1	uINT	Status switch output 2	
27	26	1	uINT	Status switch output 3	
28	27	1	uINT	Status switch output 4	

#### 4.2.5 Alarm messages

**NOTICE!** Read-only access

##### Channel 1

Reg. No.	Adr.	No. of Format Reg.	Description	Values
29	28	1	INT	<b>Message/colour change</b>
				<i>low/red</i> -2
				<i>low/yellow</i> -1
				<i>ok/green</i> 0
				<i>high/yellow</i> 1
				<i>high/red</i> 2
30	29	1	INT	<b>Acoustic alarm</b>
				<i>low</i> -1
				<i>OFF</i> 0
				<i>high</i> 1
31	30	1	uINT	<b>Confirmation acoustic alarm</b>
				<i>OFF</i> 0
				<i>ON</i> 1

##### Channel 2

Reg. No.	Adr.	No. of Format Reg.	Description	Values
32	31	1	INT	<b>Message/colour change</b>
				<i>low/red</i> -2
				<i>low/yellow</i> -1
				<i>ok/green</i> 0
				<i>high/yellow</i> 1
				<i>high/red</i> 2
33	32	1	INT	<b>Acoustic alarm</b>
				<i>low</i> -1
				<i>OFF</i> 0
				<i>high</i> 1
34	33	1	uINT	<b>Confirmation acoustic alarm</b>
				<i>OFF</i> 0
				<i>ON</i> 1

Channel 3	Reg. No.	Adr.	No. of Format Reg.	Description	Values
	35	34	1	INT	<b>Message/colour change</b>
				<i>low/red</i>	-2
				<i>low/yellow</i>	-1
				<i>ok/green</i>	0
				<i>high/yellow</i>	1
				<i>high/red</i>	2
	36	35	1	INT	<b>Acoustic alarm</b>
				<i>low</i>	-1
				<i>OFF</i>	0
				<i>high</i>	1
	37	36	1	uINT	<b>Confirmation acoustic alarm</b>
				<i>OFF</i>	0
				<i>ON</i>	1
Channel 4	Reg. No.	Adr.	No. of Format Reg.	Description	Values
	38	37	1	INT	<b>Message/colour change</b>
				<i>low/red</i>	-2
				<i>low/yellow</i>	-1
				<i>ok/green</i>	0
				<i>high/yellow</i>	1
				<i>high/red</i>	2
	39	38	1	INT	<b>Acoustic alarm</b>
				<i>low</i>	-1
				<i>OFF</i>	0
				<i>high</i>	1
	40	39	1	uINT	<b>Confirmation acoustic alarm</b>
				<i>OFF</i>	0
				<i>ON</i>	1

#### 4.2.6 Units

##### NOTICE! Read-only access

The measurement unit that is shown is the result of the configuration of the respective channel.

Reg. No.	Adr.	No. of Format Reg.	Description	max. no. Characters
41	40	3	char	Measurement unit channel 1 5
44	43	3	char	Measurement unit channel 2
47	46	3	char	Measurement unit channel 3
50	49	3	char	Measurement unit channel 4

#### 4.2.7 Unit information

**NOTICE!** Read-only access

Reg. No.	Adr.	No. of Format Reg.	Description	Values
1001	1000	8	char	Serial number
1009	1008	1	uINT	Unit code
				EA15
				0xEA15
				EA16
				0xEA16
1010	1009	1	uINT	Firmware version
1011	1010	1	uINT	Number of channels
1012	1011	1	uINT	Switching outputs
				<i>not available</i>
				0
				<i>available</i>
				1
1013	1012	1	uINT	Status SD card
				<i>SD off</i>
				0
				<i>SD ok</i>
				1
				<i>SD card almost full</i>
				2
				<i>SD card full</i>
				3
1014	1013	1	uINT	Status USB
				<i>USB off</i>
				0
				<i>USB connection</i>
				1
				<i>USB on</i>
				2
1015	1014	1	uINT	Error recognition via Modbus
				First invalid parameter

#### 4.2.8 Parameters

##### 4.2.8.1 Display

**NOTICE!** Write/read-only access

Reg. No.	Adr.	No. of Format Reg.	Description	Parameter
10001	10000	15	char	Unit designation
				Values
				max. 29 char
10016	10015	1	uINT	Date: year
				Values
				2000 .. 2099
10018	10017	1	uINT	Date: Day
				Values
				1 .. 31
10019	10018	1	uINT	Time: hours
				Values
				0 .. 23
10020	10019	1	uINT	Time: minutes
				Values
				0 .. 59
10021	10020	1	uINT	Time: seconds
				Values
				0 .. 59
10022	10021	1	uINT	Display
				List view
				0
				Tile view
				1
10023	10022	1	uINT	Colour scheme
				307

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
			<i>Colour scheme 1 (dark)</i>	0
			<i>Colour scheme 2 (light)</i>	1
<b>10024</b>	<b>10023</b>	<b>1</b>	<b>uINT</b>	<b>Brightness</b>
			100%	0
			90%	1
			80%	2
			70%	3
			60%	4
			50%	5
			40%	6
			30%	7
<b>10025</b>	<b>10024</b>	<b>1</b>	<b>uINT</b>	<b>Display</b>
			<i>Unit designation</i>	0
			<i>Date/time</i>	1
<b>10026</b>	<b>10025</b>	<b>1</b>	<b>uINT</b>	<b>Switch status</b>
			<i>hide</i>	0
			<i>show</i>	1
<b>10027</b>	<b>10026</b>	<b>1</b>	<b>uINT</b>	<b>Limit lines</b>
			<i>hide</i>	0
			<i>show</i>	1
<b>10028</b>	<b>10027</b>	<b>1</b>	<b>uINT</b>	<b>Auxiliary Lines</b>
			<i>hide</i>	0
			<i>show</i>	1
<b>10029</b>	<b>10028</b>	<b>1</b>	<b>uINT</b>	<b>Language</b>
			<i>English</i>	0
			<i>English</i>	1
			<i>Spanish</i>	2
			<i>FRENCH</i>	3
			<i>Portuguese</i>	4
			<i>Hungarian</i>	5
			<i>Italian</i>	6
<b>10030</b>	<b>10029</b>	<b>1</b>	<b>uINT</b>	<b>Date format</b>
			<i>dd.mm.yyyy</i>	0
			<i>dd/mm/yyyy</i>	1
			<i>dd-mm-yyyy</i>	2
			<i>mm.dd.yyyy</i>	3
			<i>mm/dd/yyyy</i>	4
			<i>mm-dd-yyyy</i>	5
			<i>yyyy.mm.dd</i>	6
			<i>yyyy/mm/dd</i>	7
			<i>yyyy-mm-dd</i>	8

#### 4.2.8.2 Data logger

**NOTICE! Write/read-only access**

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
10031	10030	1	uINT	Data logger
			OFF	0
			ON	1
10032	10031	1	uINT	Data logger channel 1
			OFF	0
			ON	1
10033	10032	1	uINT	Sampling rate channel 1
			125 ms	0
			250 ms	1
			500 ms	2
			1 s	3
			2 s	4
			3 s	5
			4 s	6
			5 s	7
			6 s	8
			7 s	9
			8 s	10
			9 s	11
			10 s	12
			30 s	13
			1 min	14
			5 min	15
			10 min	16
			15 min	17
			20 min	18
			30 min	19
10034	10033	1	uINT	Data logger channel 2
			OFF	0
			ON	1
10035	10034	1	uINT	Sampling rate channel 2
			125 ms	0
			250 ms	1
			500 ms	2
			1 s	3
			2 s	4
			3 s	5
			4 s	6
			5 s	7
			6 s	8
			7 s	9
			8 s	10
			9 s	11
			10 s	12
			30 s	13
			1 min	14
			5 min	15
			10 min	16
			15 min	17
			20 min	18
			30 min	19

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
<b>10036</b>	<b>10035</b>	<b>1</b>	<b>uINT</b>	<b>Data logger channel 3</b>
			OFF	0
			ON	1
<b>10037</b>	<b>10036</b>	<b>1</b>	<b>uINT</b>	<b>Sampling rate channel 3</b>
			125 ms	0
			250 ms	1
			500 ms	2
			1 s	3
			2 s	4
			3 s	5
			4 s	6
			5 s	7
			6 s	8
			7 s	9
			8 s	10
			9 s	11
			10 s	12
			30 s	13
			1 min	14
			5 min	15
			10 min	16
			15 min	17
			20 min	18
			30 min	19
<b>10038</b>	<b>10037</b>	<b>1</b>	<b>uINT</b>	<b>Data logger channel 4</b>
			OFF	0
			ON	1
<b>10039</b>	<b>10038</b>	<b>1</b>	<b>uINT</b>	<b>Sampling rate channel 4</b>
			125 ms	0
			250 ms	1
			500 ms	2
			1 s	3
			2 s	4
			3 s	5
			4 s	6
			5 s	7
			6 s	8
			7 s	9
			8 s	10
			9 s	11
			10 s	12
			30 s	13
			1 min	14
			5 min	15
			10 min	16
			15 min	17
			20 min	18
			30 min	19
<i>Event log</i>				
<b>10040</b>	<b>10039</b>	<b>1</b>	<b>uINT</b>	<b>Event log</b>
			OFF	0
			ON	1
<b>10041</b>	<b>10040</b>	<b>1</b>	<b>uINT</b>	<b>Log parameter changes</b>
				<b>340</b>

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
			OFF 0 ON 1	
10042	10041	1	uint	Log unit start 342
			OFF 0 ON 1	
10043	10042	1	uint	Log Limit thresholds 309 channel 1
			OFF 0 ON 1	
10044	10043	1	uint	Log threshold low - red chan- 314 nel 1
			OFF 0 ON 1	
10045	10044	1	uint	Log threshold low red/yellow 311 channel 1
10046	10045	1	uint	Log threshold ok/green chan- 312 nel 1
			OFF 0 ON 1	
10047	10046	1	uint	Log threshold high/yellow 310 channel 1
			OFF 0 ON 1	
10048	10047	1	uint	Log threshold high/red chan- 313 nel 1
			OFF 0 ON 1	
10049	10048	1	uint	Log Limit thresholds 317 channel 2
			OFF 0 ON 1	
10050	10049	1	uint	Log threshold low - red chan- 322 nel 2
			OFF 0 ON 1	
10051	10050	1		Log threshold low/yellow chan- 319 nel 2
			OFF 0 ON 1	
10052	10051	1	uint	Log threshold ok/green chan- 320 nel 2
			OFF 0 ON 1	
10053	10052	1	uint	Log threshold high/yellow 318 channel 2
			OFF 0 ON 1	

Reg. No.	Adr.	No. of Format Reg.	Description	Parameter
10054	10053	1	uINT	Log threshold high/red channel 2
			OFF	0
			ON	1
10055	10054	1	uINT	Log Limit thresholds channel 3
			OFF	0
			ON	1
10056	10055	1	uINT	Log threshold low - red channel 3
			OFF	0
			ON	1
10057	10056	1	uINT	Log threshold low/yellow channel 3
			OFF	0
			ON	1
10058	10057	1	uINT	Log threshold ok/green channel 3
			OFF	0
			ON	1
10059	10058	1	uINT	Log threshold high/yellow channel 3
			OFF	0
			ON	1
10060	10059	1	uINT	Log threshold high/red channel 3
			OFF	0
			ON	1
10061	10060	1	uINT	Log Limit thresholds channel 4
			OFF	0
			ON	1
10062	10061	1	uINT	Log threshold low - red channel 4
			OFF	0
			ON	1
10063	10062	1	uINT	Log threshold low/yellow channel 4
			OFF	0
			ON	1
10064	10063	1	uINT	Log threshold ok/green channel 4
			OFF	0
			ON	1
10065	10064	1	uINT	Log threshold high/yellow channel 4
			OFF	0
			ON	1
10066	10065	1	uINT	Log threshold high/red channel 4
			OFF	0
			ON	1

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
10067	10066	1	uINT	<b>Log switch output 1</b> 343
			OFF	0
			ON	1
10068	10067	1	uINT	<b>Log switch output 2</b> 344
			OFF	0
			ON	1
10069	10068	1	uINT	<b>Log switch output 3</b> 345
			OFF	0
			ON	1
10070	10069	1	uINT	<b>Log switch output 4</b> 346
			OFF	0
			ON	1

#### 4.2.8.3 RS485 Interface / Modbus

**NOTICE!** Read-only access

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
10202	10201	1	uINT	<b>Baud rate</b> 405
			1200 baud	0
			2400 baud	1
			4800 baud	2
			9600 baud	3
			19200 baud	4
			38400 baud	5
			57600 baud	6
10203	10202	1	uINT	<b>Data format</b> 406
			8 data bit no parity 1 stop bit	0
			8 data bit no parity 2 stop bit	1
			8 data bit uneven parity 1 stop bit	2
			8 data bit uneven parity 2 stop bit	3
			8 data bit even parity 1 stop bit	4
			8 data bit even parity 2 stop bit	5
10204	10203	1	uINT	<b>Slave address</b> 404
			1 .. 255	
10205	10204	2	uINT	<b>Waiting time Telegram end recognition</b> 407
			0 .. 10,000 ms	

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
10207	10206	1	uINT <b>Byte sequence comprised values</b>	408
			Big Endian	0
			Little Endian	1

#### 4.2.8.4 Analogue inputs

##### 4.2.8.4.1 Analogue input 1

**NOTICE! Write/read-only access**

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr. Reg.	No. of Format	Description	Para- meter
11001	11000	5	char	Planned measures
			max. 8 characters	21
<i>Input signal</i>				
11006	11005	1	uINT	Type:
			Electricity	0
			Voltage	1
11007	11006	2	Float	Signal min.
			Electricity	0 .. 20.5 mA
11009	11008	2	Float	Signal max.
			Electricity	0 .. 20.5 mA
11011	11010	2	Float	Signal min.
			Voltage	0 .. 10.5 V
11013	11012	2	Float	Signal max.
			Voltage	0 .. 10.5 V
11015	11014	1	—	—
			always	0
<i>Pres. of measurem.</i>				
11016	11015	1	uINT	Receipt
			Active	0
			Inactive	1
11017	11016	1	uINT	Integer digits
			Value	1 .. 6
11018	11017	1	uINT	Decimal Places
			Value	0 .. 3
11019	11018	1	—	—
			always	0
<i>Messages / Colour change</i>				
11020	11019	2	Float	Hysteresis
			Value	0 ..  Measuring range
11022	11021	2	Float	Deceleration
			Value	0 .. 3,600,000 ms
11024	11023	1	uINT	Threshold low - red:
			Off	0
			on	1
11025	11024	2	Float	Threshold low - red:
			Threshold	MBA - $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter	
11027	11026	1	uINT	<b>Threshold low - yellow</b> Off 0 on 1	43
11028	11027	2	Float	<b>Threshold low - yellow</b> Threshold MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB	47
11030	11029	1	uINT	<b>Threshold high - yellow</b> Off 0 on 1	42
11031	11030	2	Float	<b>Threshold high - yellow</b> Threshold MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB	46
11033	11032	1	uINT	<b>Threshold high - red</b> Off 0 on 1	44
11034	11033	2	Float	<b>Threshold high - red</b> Threshold MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB	48
11036	11035	1	uINT	<b>News</b> Off 0 on 1	36
11037	11036	25	char	<b>Message low - red</b> Text max. 49 characters	37
11062	11061	25	char	<b>Message low - yellow</b> Text max. 49 characters	38
11087	11086	25	char	<b>Message ok - green</b> Text max. 49 characters	39
11112	11111	25	char	<b>Message high - yellow</b> Text max. 49 characters	40
11137	11136	25	char	<b>Message high - red</b> Text max. 49 characters	41
<i>Acoustic alarm</i>					
11162	11161	1	uINT	<b>Alert</b> Off 0 on 1	365
11163	11162	1	uINT	<b>Alarm low</b> Off 0 on 1	364
11164	11163	2	Float	<b>Threshold low ON</b> Threshold MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB	369

Reg. No.	Adr. No.	No. of Format Reg.	Description	Para- meter
11166	11165	2	Float	<b>Threshold low OFF</b> 368
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
11168	11167	2	uINT	<b>Delay low</b> 361
				0 ... 3,600,000 ms
11170	11169	1	uINT	<b>Alarm high</b> 363
			Off	0
			on	1
11171	11170	2	Float	<b>Threshold high ON</b> 367
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
11173	11172	2	Float	<b>Threshold high OFF</b> 366
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
11175	11174	2	uINT	<b>Delay high</b> 360
			Value	0 ... 3.600.00 ms
11177	11176	1	uINT	<b>Accept</b> 362
			Off	0
			on	1
11178	11177	2	uINT	<b>Confirmation of process</b> 359
			Value	0 ... 7,200,000 ms
<i>Characteristic curve</i>				
11180	11179	1	uINT	<b>Function</b> 32
			linear	0
			root extracted	1
			Flow	2
11181	11180	3	char	<b>Unit</b> 280
			Lin. scaling	max. 5 characters
11184	11183	2	Float	<b>Measuring range start</b> 289
			Lin. scaling	±999,999
11186	11185	2	Float	<b>Measuring range end</b> 288
			Lin. scaling	±999,999
11188	11187	2	Float	<b>Zero-point window</b> 29
			Value	0 .. 25 %
11190	11189	3	char	<b>Unit</b> 284
			Non-lin. scal-	ing
				max. 5 characters
11193	11192	2	Float	<b>Measuring range start</b> 291
			Non-lin. scaling	±999,999
11195	11194	2	Float	<b>Measuring range end</b> 290
			Non-lin. scaling	±999,999
11197	11196	2	Float	<b>k-factor (not implemented at this time)</b> 33
			Value	±10,000
11199	11198	2	uINT	<b>Attenuation</b> 28
			Value	0 ... 30,000 ms

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
11201	11200	2	Float	Offset correction
			Value	- Measuring range  ...  Measuring range
11203	11202	1	uINT	Limits
			Off	0
			on	1

#### 4.2.8.4.2 Analogue input 2

##### NOTICE! Write/read-only access

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
12001	12000	5	char	Planned measures
				max. 8 characters
				<i>Input signal</i>
12006	12005	1	uINT	Type:
				Electricity 0
				Voltage 1
12007	12006	2	Float	Signal min.
				Electricity 0 .. 20.5 mA
12009	12008	2	Float	Signal max.
				Electricity 0 .. 20.5 mA
12011	12010	2	Float	Signal min.
				Voltage 0 .. 10.5 V
12013	12012	2	Float	Signal max.
				Voltage 0 .. 10.5 V
12015	12014	1	—	—
				always 0
				<i>Pres. of measurem.</i>
12016	12015	1	uINT	Receipt
				Active 0
				Inactive 1
12017	12016	1	uINT	Integer digits
				Value 1 .. 6
12018	12017	1	uINT	Decimal Places
				Value 0 .. 3
12019	12018	1	—	—
				always 0
				<i>Messages / Colour change</i>
12020	12019	2	Float	Hysteresis
				Value 0 ..  Measuring range
12022	12021	2	Float	Deceleration
				Value 0 .. 3,600,000 ms

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
12024	12023	1	uINT	<b>Threshold low - red:</b>
			Off	0
			on	1
12025	12024	2	Float	<b>Threshold low - red:</b>
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12027	12026	1	uINT	<b>Threshold low - yellow</b>
			Off	0
			on	1
12028	12027	2	Float	<b>Threshold low - yellow</b>
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12030	12029	1	uINT	<b>Threshold high - yellow</b>
			Off	0
			on	1
12031	12030	2	Float	<b>Threshold high - yellow</b>
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12033	12032	1	uINT	<b>Threshold high - red</b>
			Off	0
			on	1
12034	12033	2	Float	<b>Threshold high - red</b>
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12036	12035	1	uINT	<b>News</b>
			Off	0
			on	1
12037	12036	25	char	<b>Message low - red</b>
			Text	max. 49 charac- ters
12062	12061	25	char	<b>Message low - yellow</b>
			Text	max. 49 charac- ters
12087	12086	25	char	<b>Message ok - green</b>
			Text	max. 49 charac- ters
12112	12111	25	char	<b>Message high - yellow</b>
			Text	max. 49 charac- ters
12137	12136	25	char	<b>Message high - red</b>
			Text	max. 49 charac- ters
<i>Acoustic alarm</i>				
12162	12161	1	uINT	<b>Alert</b>
			Off	0
			on	1
12163	12162	1	uINT	<b>Alarm low</b>
			Off	0

Reg. No.	Adr.	No. of Format Reg.	Description	Parameter
			on	1
12164	12163	2	<b>Float</b>	<b>Threshold low ON</b> 380
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12166	12165	2	<b>Float</b>	<b>Threshold low OFF</b> 379
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12168	12167	2	<b>uINT</b>	<b>Delay low</b> 372
				0 ... 3,600,000 ms
12170	12169	1	<b>uINT</b>	<b>Alarm high</b> 374
			Off	0
			on	1
12171	12170	2	<b>Float</b>	<b>Threshold high ON</b> 378
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12173	12172	2	<b>Float</b>	<b>Threshold high OFF</b> 377
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
12175	12174	2	<b>uINT</b>	<b>Delay high</b> 371
			Value	0 ... 3,600.00 ms
12177	12176	1	<b>uINT</b>	<b>Accept</b> 373
			Off	0
			on	1
12178	12177	2	<b>uINT</b>	<b>Confirmation of process</b> 370
			Value	0 ... 7,200,000 ms
<i>Characteristic curve</i>				
12180	12179	1	<b>uINT</b>	<b>Function</b> 64
			linear	0
			root extracted	1
			Flow	2
12181	12180	3	<b>char</b>	<b>Unit</b> 281
			Lin. scaling	max. 5 characters
12184	12183	2	<b>Float</b>	<b>Measuring range start</b> 293
			Lin. scaling	±999,999
12186	12185	2	<b>Float</b>	<b>Measuring range end</b> 292
			Lin. scaling	±999,999
12188	12187	2	<b>Float</b>	<b>Zero-point window</b> 61
			Value	0 .. 25 %
12190	12189	3	<b>char</b>	<b>Unit</b> 285
			Non-lin. scal-	ing
				max. 5 characters
12193	12192	2	<b>Float</b>	<b>Measuring range start</b> 295
			Non-lin. scaling	±999,999
12195	12194	2	<b>Float</b>	<b>Measuring range end</b> 294
			Non-lin. scaling	±999,999

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
12197	12196	2	Float	k-factor (not implemented at this time)
			Value	±10,000
12199	12198	2	uINT	Attenuation
			Value	0 ... 30,000 ms
12201	12200	2	Float	Offset correction
			Value	- Measuring range  ...  Measuring range
12203	12202	1	uINT	Limits
			Off	0
			on	1

#### 4.2.8.4.3 Analogue input 3

##### NOTICE! Write/read-only access

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
13001	13000	5	char	Planned measures
				max. 8 characters
<i>Input signal</i>				
13006	13005	1	uINT	Type:
				Electricity 0
				Voltage 1
13007	13006	2	Float	Signal min.
				Electricity 0 .. 20.5 mA
13009	13008	2	Float	Signal max.
				Electricity 0 .. 20.5 mA
13011	13010	2	Float	Signal min.
				Voltage 0 .. 10.5 V
13013	13012	2	Float	Signal max.
				Voltage 0 .. 10.5 V
13015	13014	1	—	—
				always 0
<i>Pres. of measurem.</i>				
13016	13015	1	uINT	Receipt
				Active 0
				Inactive 1
13017	13016	1	uINT	Integer digits
				Value 1 .. 6
13018	13017	1	uINT	Decimal Places
				Value 0 .. 3
13019	13018	1	—	—
				always 0

Reg. No.	Adr.	No. of Format Reg.	Description	Parameter
<i>Messages / Colour change</i>				
13020	13019	2	Float	Hysteresis 115
			Value	0 ..  Measuring range
13022	13021	2	Float	Deceleration 114
			Value	0 .. 3,600,000 ms
13024	13023	1	uINT	Threshold low - red: 109
			Off	0
			on	1
13025	13024	2	Float	Threshold low - red: 113
			Threshold	MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB
13027	13026	1	uINT	Threshold low - yellow 107
			Off	0
			on	1
13028	13027	2	Float	Threshold low - yellow 111
			Threshold	MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB
13030	13029	1	uINT	Threshold high - yellow 106
			Off	0
			on	1
13031	13030	2	Float	Threshold high - yellow 110
			Threshold	MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB
13033	13032	1	uINT	Threshold high - red 108
			Off	0
			on	1
13034	13033	2	Float	Threshold high - red 112
			Threshold	MBA – $\frac{1}{2}$  MB  ... MBE + $\frac{1}{2}$  MB
13036	13035	1	uINT	News 100
			Off	0
			on	1
13037	13036	25	char	Message low - red 101
			Text	max. 49 characters
13062	13061	25	char	Message low - yellow 102
			Text	max. 49 characters
13087	13086	25	char	Message ok - green 103
			Text	max. 49 characters
13112	13111	25	char	Message high - yellow 104
			Text	max. 49 characters
13137	13136	25	char	Message high - red 105
			Text	max. 49 characters

Reg. No.	Adr.	No. of Format Reg.	Description	Parameter
<i>Acoustic alarm</i>				
13162	13161	1	uINT	<b>Alert</b> 387
			Off	0
			on	1
13163	13162	1	uINT	<b>Alarm low</b> 386
			Off	0
			on	1
13164	13163	2	Float	<b>Threshold low ON</b> 391
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
13166	13165	2	Float	<b>Threshold low OFF</b> 390
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
13168	13167	2	uINT	<b>Delay low</b> 383
			Value	0 ... 3,600,000 ms
13170	13169	1	uINT	<b>Alarm high</b> 385
			Off	0
			on	1
13171	13170	2	Float	<b>Threshold high ON</b> 389
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
13173	13172	2	Float	<b>Threshold high OFF</b> 388
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
13175	13174	2	uINT	<b>Delay high</b> 382
			Value	0 ... 3.600.00 ms
13177	13176	1	uINT	<b>Accept</b> 384
			Off	0
			on	1
13178	13177	2	uINT	<b>Confirmation of process</b> 381
			Value	0 ... 7,200,000 ms
<i>Characteristic curve</i>				
13180	13179	1	uINT	<b>Function</b> 96
			linear	0
			root extracted	1
			Flow	2
13181	13180	3	char	<b>Unit</b> 282
			Lin. scaling	max. 5 characters
13184	13183	2	Float	<b>Measuring range start</b> 297
			Lin. scaling	±999,999
13186	13185	2	Float	<b>Measuring range end</b> 296
			Lin. scaling	±999,999
13188	13187	2	Float	<b>Zero-point window</b> 93
			Value	0 .. 25 %
13190	13189	3	char	<b>Unit</b> 286
			Non-lin. scal-	ing max. 5 characters

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
13193	13192	2	Float	<b>Measuring range start</b> 299
			Non-lin. scaling	$\pm 999,999$
13195	13194	2	Float	<b>Measuring range end</b> 298
			Non-lin. scaling	$\pm 999,999$
13197	13196	2	Float	<b>k-factor (not implemented at this time)</b> 97
			Value	$\pm 10,000$
13199	13198	2	uINT	<b>Attenuation</b> 92
			Value	0 ... 30,000 ms
13201	13200	2	Float	<b>Offset correction</b> 94
			Value	$- Measuring range  \dots  Measuring range $
13203	13202	1	uINT	<b>Limits</b> 95
			Off	0
			on	1

#### 4.2.8.4.4 Analogue input 4

##### NOTICE! Write/read-only access

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
14001	14000	5	char	<b>Planned measures</b> 117
			max. 8 characters	
<i>Input signal</i>				
14006	14005	1	uINT	<b>Type:</b> 271
			Electricity	0
			Voltage	1
14007	14006	2	Float	<b>Signal min.</b> 273
			Electricity	0 .. 20.5 mA
14009	14008	2	Float	<b>Signal max.</b> 272
			Electricity	0 .. 20.5 mA
14011	14010	2	Float	<b>Signal min.</b> 275
			Voltage	0 .. 10.5 V
14013	14012	2	Float	<b>Signal max.</b> 274
			Voltage	0 .. 10.5 V
14015	14014	1	—	—
			always	0
<i>Pres. of measurem.</i>				
14016	14015	1	uINT	<b>Receipt</b> 415
			Active	0
			Inactive	1
14017	14016	1	uINT	<b>Integer digits</b> 120
			Value	1 .. 6

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
14018	14017	1	uINT	<b>Decimal Places</b> <b>119</b>
			Value	0 .. 3
14019	14018	1	—	—
			always	0
<i>Messages / Colour change</i>				
14020	14019	2	Float	<b>Hysteresis</b> <b>147</b>
			Value	0 ..  Measuring range
14022	14021	2	Float	<b>Deceleration</b> <b>146</b>
			Value	0 .. 3,600,000 ms
14024	14023	1	uINT	<b>Threshold low - red:</b> <b>141</b>
			Off	0
			on	1
14025	14024	2	Float	<b>Threshold low - red:</b> <b>145</b>
			Threshold	MBA - $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14027	14026	1	uINT	<b>Threshold low - yellow</b> <b>139</b>
			Off	0
			on	1
14028	14027	2	Float	<b>Threshold low - yellow</b> <b>143</b>
			Threshold	MBA - $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14030	14029	1	uINT	<b>Threshold high - yellow</b> <b>138</b>
			Off	0
			on	1
14031	14030	2	Float	<b>Threshold high - yellow</b> <b>142</b>
			Threshold	MBA - $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14033	14032	1	uINT	<b>Threshold high - red</b> <b>140</b>
			Off	0
			on	1
14034	14033	2	Float	<b>Threshold high - red</b> <b>144</b>
			Threshold	MBA - $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14036	14035	1	uINT	<b>News</b> <b>132</b>
			Off	0
			on	1
14037	14036	25	char	<b>Message low - red</b> <b>133</b>
			Text	max. 49 characters
14062	14061	25	char	<b>Message low - yellow</b> <b>134</b>
			Text	max. 49 characters
14087	14086	25	char	<b>Message ok - green</b> <b>135</b>
			Text	max. 49 characters

Reg. No.	Adr.	No. of Format Reg.	Description	Parameter
14112	14111	25	char	<b>Message high - yellow</b> 136
			Text	max. 49 characters
14137	14136	25	char	<b>Message high - red</b> 137
			Text	max. 49 characters
<i>Acoustic alarm</i>				
14162	14161	1	uINT	<b>Alert</b> 398
			Off	0
			on	1
14163	14162	1	uINT	<b>Alarm low</b> 397
			Off	0
			on	1
14164	14163	2	Float	<b>Threshold low ON</b> 402
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14166	14165	2	Float	<b>Threshold low OFF</b> 401
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14168	14167	2	uINT	<b>Delay low</b> 394
			Value	0 ... 3,600,000 ms
14170	14169	1	uINT	<b>Alarm high</b> 396
			Off	0
			on	1
14171	14170	2	Float	<b>Threshold high ON</b> 400
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14173	14172	2	Float	<b>Threshold high OFF</b> 399
			Threshold	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
14175	14174	2	uINT	<b>Delay high</b> 393
			Value	0 ... 3,600.00 ms
14177	14176	1	uINT	<b>Accept</b> 395
			Off	0
			on	1
14178	14177	2	uINT	<b>Confirmation of process</b> 392
			Value	0 ... 7,200,000 ms
<i>Characteristic curve</i>				
14180	14179	1	uINT	<b>Function</b> 128
			linear	0
			root extracted	1
			Flow	2
14181	14180	3	char	<b>Unit</b> 283
			Lin. scaling	max. 5 characters
14184	14183	2	Float	<b>Measuring range start</b> 301
			Lin. scaling	±999,999

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
14186	14185	2	Float	<b>Measuring range end</b> 300
			Lin. scaling	±999,999
14188	14187	2	Float	<b>Zero-point window</b> 125
			Value	0 .. 25 %
14190	14189	3	char	<b>Unit</b> 287
			Non-lin. scal-	ing max. 5 characters
14193	14192	2	Float	<b>Measuring range start</b> 303
			Non-lin. scaling	±999,999
14195	14194	2	Float	<b>Measuring range end</b> 302
			Non-lin. scaling	±999,999
14197	14196	2	Float	<b>k-factor (not implemented at this time)</b> 129
			Value	±10,000
14199	14198	2	uINT	<b>Attenuation</b> 124
			Value	0 ... 30,000 ms
14201	14200	2	Float	<b>Offset correction</b> 126
			Value	- Measuring range  ...  Measuring range
14203	14202	1	uINT	<b>Limits</b> 127
			Off	0
			on	1

#### 4.2.8.5 Analogue outputs

##### 4.2.8.5.1 Analogue output 1

**NOTICE! Write/read-only access**

Reg. No.	Adr. 15000	No. of Format Reg.	Description	Para- meter
15001	15000	1	uINT	<b>Assignment</b>
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4
15002	15001	1	uINT	<b>Type</b>
			Electricity	0
			Voltage	1
15003	15002	2	Float	<b>Output min.</b>
			Electricity	0 ... 21.5 mA
15005	15004	2	Float	<b>Output max.</b>
			Electricity	0 ... 21.5 mA
15007	15006	2	Float	<b>Output min.</b>
			Voltage	0 ... 10.5 V
15009	15008	2	Float	<b>Output max.</b>
			Voltage	0 ... 10.5 V
15011	15010	2	Float	<b>Limit min.</b>
			Electricity	0 ... 21.5 mA
15013	15012	2	Float	<b>Limit max.</b>
			Electricity	0 ... 21.5 mA
15015	15014	2	Float	<b>Limit min.</b>
			Voltage	0 ... 10.5 V
15017	15016	2	Float	<b>Limit max.</b>
			Voltage	0 ... 10.5 V
15019	15018	2	Float	<b>Error signal</b>
			Electricity	0 ... 21.5 mA
15021	15020	2	Float	<b>Error signal</b>
			Voltage	0 ... 10.5 V
15023	15022	3	—	—
			always	0

##### 4.2.8.5.2 Analogue output 2

**NOTICE! Write/read-only access**

Reg. No.	Adr. 15025	No. of Format Reg.	Description	Para- meter
15026	15025	1	uINT	<b>Assignment</b>
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
15027	15026	1	uINT	Type
			Electricity	0
			Voltage	1
15028	15027	2	Float	Output min.
			Electricity	0 .. 21.5 mA
15030	15029	2	Float	Output max.
			Electricity	0 .. 21.5 mA
15032	15031	2	Float	Output min.
			Voltage	0 .. 10.5 V
15034	15033	2	Float	Output max.
			Voltage	0 .. 10.5 V
15036	15035	2	Float	Limit min.
			Electricity	0 .. 21.5 mA
15038	15037	2	Float	Limit max.
			Electricity	0 .. 21.5 mA
15040	15039	2	Float	Limit min.
			Voltage	0 .. 10.5 V
15042	15041	2	Float	Limit max.
			Voltage	0 .. 10.5 V
15044	15043	2	Float	Error signal
			Electricity	0 .. 21.5 mA
15046	15045	2	Float	Error signal
			Voltage	0 .. 10.5 V
15048	15047	3	—	—
			always	0

#### 4.2.8.5.3 Analogue output 3

NOTICE! Write/read-only access

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
15051	15050	1	uINT	Assignment
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4
15052	15051	1	uINT	Type
			Electricity	0
			Voltage	1
15053	15052	2	Float	Output min.
			Electricity	0 .. 21.5 mA
15055	15054	2	Float	Output max.
			Electricity	0 .. 21.5 mA
15057	15056	2	Float	Output min.
			Voltage	0 .. 10.5 V

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
15059	15058	2	Float	Output max.
			Voltage	0 .. 10.5 V
15061	15060	2	Float	Limit min.
			Electricity	0 .. 21.5 mA
15063	15062	2	Float	Limit max.
			Electricity	0 .. 21.5 mA
15065	15064	2	Float	Limit min.
			Voltage	0 .. 10.5 V
15067	15066	2	Float	Limit max.
			Voltage	0 .. 10.5 V
15069	15068	2	Float	Error signal
			Electricity	0 .. 21.5 mA
15071	15070	2	Float	Error signal
			Voltage	0 .. 10.5 V
15073	15072	3	—	—
			always	0

#### 4.2.8.5.4 Analogue output 4

**NOTICE!** Write/read-only access

Reg. No.	Adr. Reg.	No. of Format Reg.	Description	Para- meter
15076	15075	1	uINT	Assignment
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4
15077	15076	1	uINT	Type
			Electricity	0
			Voltage	1
15078	15077	2	Float	Output min.
			Electricity	0 .. 21.5 mA
15080	15079	2	Float	Output max.
			Electricity	0 .. 21.5 mA
15082	15081	2	Float	Output min.
			Voltage	0 .. 10.5 V
15084	15083	2	Float	Output max.
			Voltage	0 .. 10.5 V
15086	15085	2	Float	Limit min.
			Electricity	0 .. 21.5 mA
15088	15087	2	Float	Limit max.
			Electricity	0 .. 21.5 mA
15090	15089	2	Float	Limit min.
			Voltage	0 .. 10.5 V
15092	15091	2	Float	Limit max.
			Voltage	0 .. 10.5 V

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter	
15094	15093	2	Float	<b>Error signal</b> Electricity 0 .. 21.5 mA	227
15096	15096	2	Float	<b>Error signal</b> Voltage 0 .. 10.5 V	234
15098	15097	3	—	— always 0	—

## 4.2.8.6 Switching outputs

### 4.2.8.6.1 Switching output 1

**NOTICE! Write/read-only access**

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr. 16000	No. of Format Reg.	Description	Para- meter
16001	16000	1	<b>Assignment</b>	148
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4
16002	16001	1	<b>Contact type</b>	150
			Make contact	0
			Break contact	1
16003	16002	1	<b>Function</b>	149
			Hysteresis	0
			Window	1
16004	16003	2	<b>Switch-on point and/or Window max.</b>	152
			Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
16006	16005	2	<b>Switch-off point and/or Window min.</b>	153
			Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
16008	16007	2	<b>Switching delay</b>	151
			Value	0 ... 10,800,000 ms

### 4.2.8.6.2 Switching output 2

**NOTICE! Write/read-only access**

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr. 16009	No. of Format Reg.	Description	Para- meter
16010	16009	1	<b>Assignment</b>	154
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4
16011	16010	1	<b>Contact type</b>	156
			Make contact	0
			Break contact	1

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
16012	16011	1	uINT	<b>Function</b>
			Hysteresis	0
			Window	1
16013	16012	2	Float	<b>Switch-on point and/or Window max.</b>
			Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
16015	16014	2	Float	<b>Switch-off point and/or Window min.</b>
			Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
16017	16016	2	uINT	<b>Switching delay</b>
			Value	0 ... 10,800,000 ms

#### 4.2.8.6.3 Switching output 3

##### NOTICE! Write/read-only access

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr.	No. of Format Reg.	Description	Para- meter
16019	16018	1	uINT	<b>Assignment</b>
			Not assigned	0
			Channel 1	1
			Channel 2	2
			Channel 3	3
			Channel 4	4
16020	16019	1	uINT	<b>Contact type</b>
			Make contact	0
			Break contact	1
16021	16020	1	uINT	<b>Function</b>
			Hysteresis	0
			Window	1
16022	16021	2	Float	<b>Switch-on point and/or Window max.</b>
			Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
16024	16023	2	Float	<b>Switch-off point and/or Window min.</b>
			Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
16026	16025	2	uINT	<b>Switching delay</b>
			Value	0 ... 10,800,000 ms

#### 4.2.8.6.4 Switching output 4

##### NOTICE! Write/read-only access

MB: measuring range

MBA: start of measuring range

MBE; end of the measuring range

Reg. No.	Adr. 16027	No. of Reg. 1	Format uINT	Description	Para- meter
<b>16028</b>	<b>16027</b>	<b>1</b>	<b>uINT</b>	<b>Assignment</b>	<b>166</b>
				Not assigned	0
				Channel 1	1
				Channel 2	2
				Channel 3	3
				Channel 4	4
<b>16029</b>	<b>16028</b>	<b>1</b>	<b>uINT</b>	<b>Contact type</b>	<b>168</b>
				Make contact	0
				Break contact	1
<b>16030</b>	<b>16029</b>	<b>1</b>	<b>uINT</b>	<b>Function</b>	<b>167</b>
				Hysteresis	0
				Window	1
<b>16031</b>	<b>16030</b>	<b>2</b>	<b>Float</b>	<b>Switch-on point and/or Window max.</b>	<b>170</b>
				Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
<b>16033</b>	<b>16032</b>	<b>2</b>	<b>Float</b>	<b>Switch-off point and/or Window min.</b>	<b>171</b>
				Value	MBA – $\frac{1}{2} MB $ ... MBE + $\frac{1}{2} MB $
<b>16035</b>	<b>16034</b>	<b>2</b>	<b>uINT</b>	<b>Switching delay</b>	<b>169</b>
				Value	0 ... 10,800,000 ms

## 5 Glossary

### ADU

The Application Data Unit (ADU) is the complete command / data block of the communication protocol.

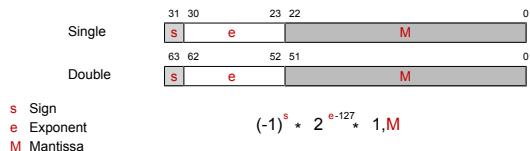
### char

Abbreviation for character Char as a data type defines that the individual characters of a memory area each comprise (usually) 8 bits that represent a displayable character (letter, digit, special character...). The content of the memory point states which sign this is.

### EIA-485

EIA-485, also called RS-485, is an industrial standard for an interface with asynchronous serial data transmission.

### IEEE-475



The IEEE754 standard stipulates several data formats. The most important are the single and the double format. These formats comprise a sign bit s, the exponent e and the mantissa m.

### Master/Slave

Master/Slave is a type of hierarchical administration of access to a common resource usually in the shape of a common data channel. A participant is the Master, all others are the Slaves. The Master is the only one authorised to access the joint resource without request. The Slave cannot access the common resource on its own; it must wait until it is requested by the Master.

### Message

Process of the transmission of data between a sender and one or more recipients.

### PDU

The Protocol Data Unit (PDU) is the data block of a message.

### Request

The request by a Master to a Slave to carry out the Function Code the transmission contains.

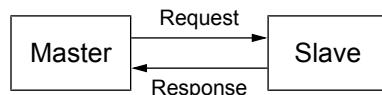
### Response

Response by the Slave to the Master to a Request.

### RTU

Remote Terminal Unit

### Transaction



A transaction comprises a request from the Master and a response from the Slave.

## 6 Attachments

### 6.1 Literature

„IEEE Standard for Floating-Point Arithmetic.“ 29. 08 2008.  
<http://ieeexplore.ieee.org/document/4610935/>.

„Modbus Application Protocol v1.1b3.“ 26. 04 2012.  
[http://www.modbus.org/docs/Modbus\\_Application\\_Protocol\\_V1\\_1b3.pdf](http://www.modbus.org/docs/Modbus_Application_Protocol_V1_1b3.pdf).

### 6.2 Changes

2017-01-13 First issued

